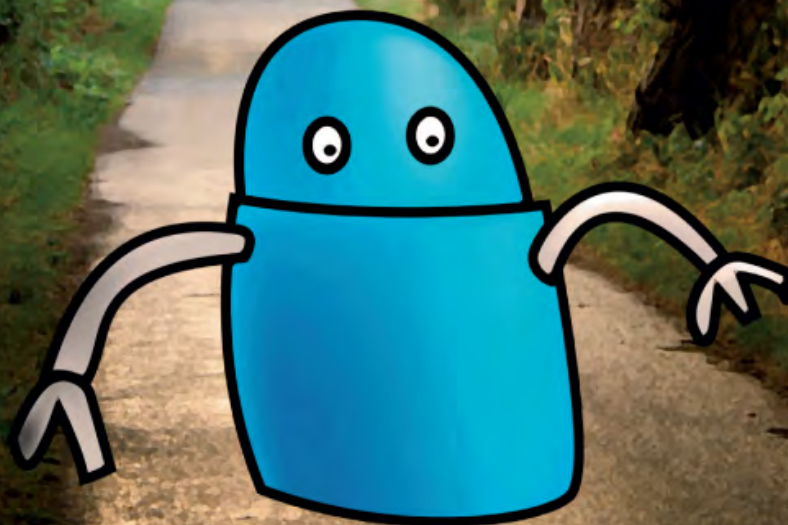
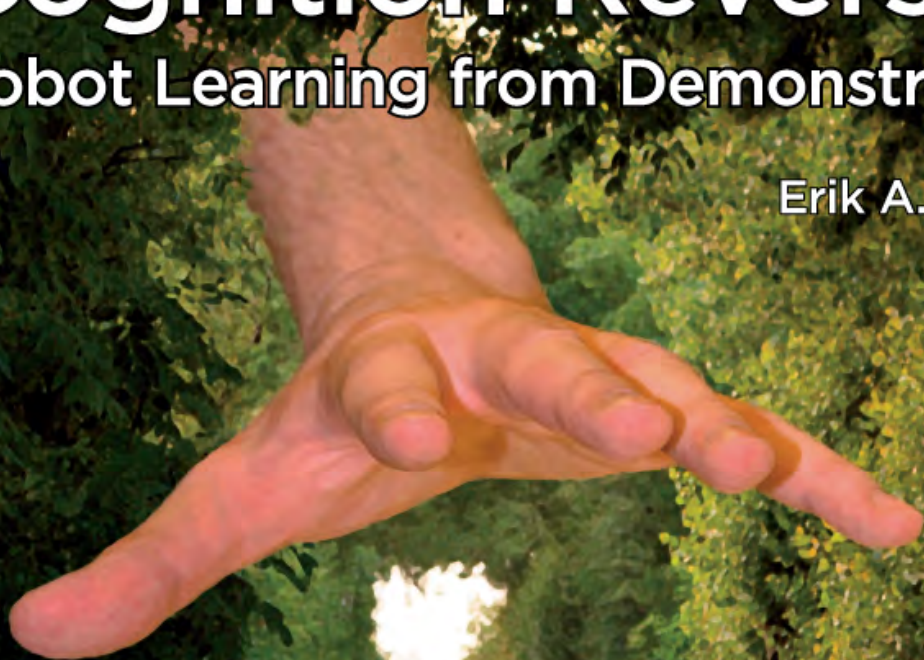


Cognition Reversed

Robot Learning from Demonstration

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Licentiate Thesis, 2009
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